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INFORMATION DISCLOSURE STATEMENT BY APPLICANT

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Complete if Known				
Application Number 10/662,653-Conf. #9391				
Filing Date	September 15, 2003			
First Named Inventor	Michael P. Nowak			
Art Unit	2863			
Examiner Name	T. S. Lau			
Attorney Docket Number	65858-0026/02-rASD-183			

U.S. PATENT DOCUMENTS					
Examiner Initials*	Cite No.	Document Number Number-Kind Code ² (if known)	Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear
TL	AA	US-5,850,469-A	12-15-1998	Martin et al.	

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Examiner Initials*	Cite No.¹	Foreign Patent Document Country Code ⁸ -Number ⁴ -Kind Code ⁶ (if known)	Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Unes, Where Relevant Passages or Relevant Figures Appear	™
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NON PATENT LITERATURE DOCUMENTS					
Examiner Cite Initials No.1		Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.			
41-	CA	PCT International Search Report (4 pages)			
71	СВ	Borgefors, Gunilla; "Hierarchical Chamfer Matching: A Parametric Edge Matching Algorithm"; IEEE Transactions On Pattern Analysis And Machine Intelligence; IEEE Inc., New York; Vol. 10, No. 6, November 1988; pgs. 849-865; XP002114858			
Th	CC	Cobzas, Dana, et al.; "Image-Based Localization With Depth-Enhanced Image Map"; PROC2003 INT.; IEEE Conf. Robotics and Automation; Vol. 2, September 14, 2003; pgs. 1570-1575, XP010667213			
7	CD	Horn, Joachim, et al.; "Localization Of A Mobile Robot By Matching 3D-Laser-Range-Images And Predicted Sensor Images"; Intelligent Vehicles '94 Symposium, Paris, 24 October 1994; pgs. 345-350; XP010258393			
1	CE	Zingaretti, P. et al.; "Image Segmentation For Apperance-Based Self-Localisation"; 11th International Conference On Image Analysis And Processing; September 26, 2001; pgs. 113-118; XP010561233			
TL	CF	Dudek, Gregory, et al.; "Vision-Based Robot Localization Without Explicit Object Models"; Proceedings of the 1996 IEEE International Conference on Robotics And Automation; Minneapolis, MN; April 22-28, 1996; pgs. 76-82; XP010162733			

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